

Peter Pazmany Catholic University, Budapest

Cellular Wave Computers

Analogic Cellular PDE Machines

Course Material

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Contents

- Analogic PDE Machines
- PDE formulation of reaction-diffusion processes
- Implementation of active contour methods in target detection and tracking
- Implementation of wave-metrics in object comparison and classification
- PDE formulation of contrast enhancement with denoising
- Implementation of contrast enhancement methods with denoising
- Summary

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Preliminaries:

- ◆ Cellular Automata are an alternative to (rather than an approximation of) differential equations in modeling physics /Toffoli, 1984/
- ◆ There are cellular structures described by ODEs for which a limiting PDE with the same qualitative properties does not exist /Keener, 1987/
- ◆ The spectrum of the volume of any physical region is discrete /Rovelli-Smolín, 1995/
- ◆ PDEs are merely idealizations of cellular structures described by coupled ODEs or local rules /Chua, 1997/

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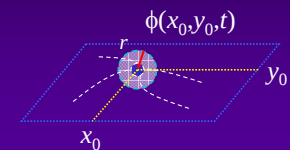
Local and Global PDEs

Local PDE:

- the evolution of the system at any location depends only on local properties

$$\dot{\phi}_r(x, y, t) = \Gamma(\phi_r(x, y, t))$$

$$\{ \forall (x_0, y_0, t) \mid r \rightarrow 0 \Rightarrow \Gamma = \Gamma(x_0, y_0, t) \}$$

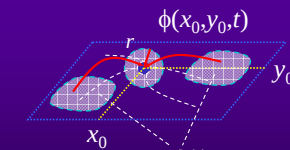


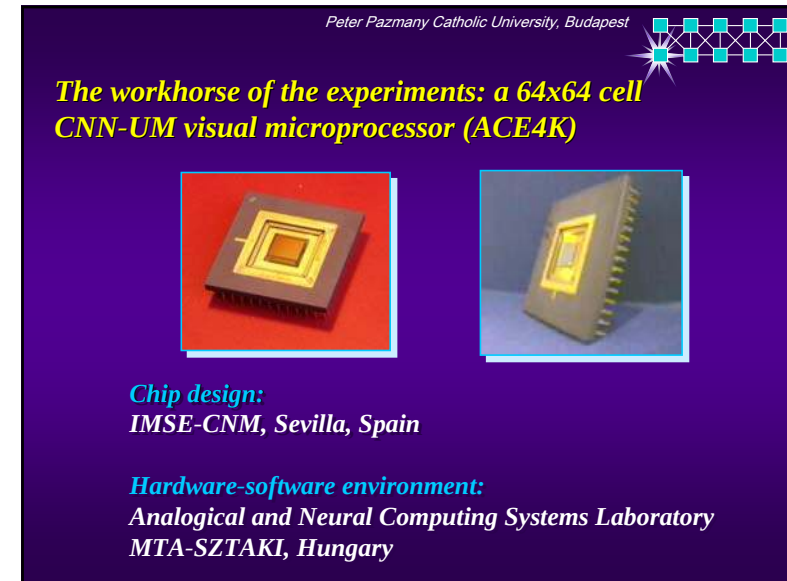
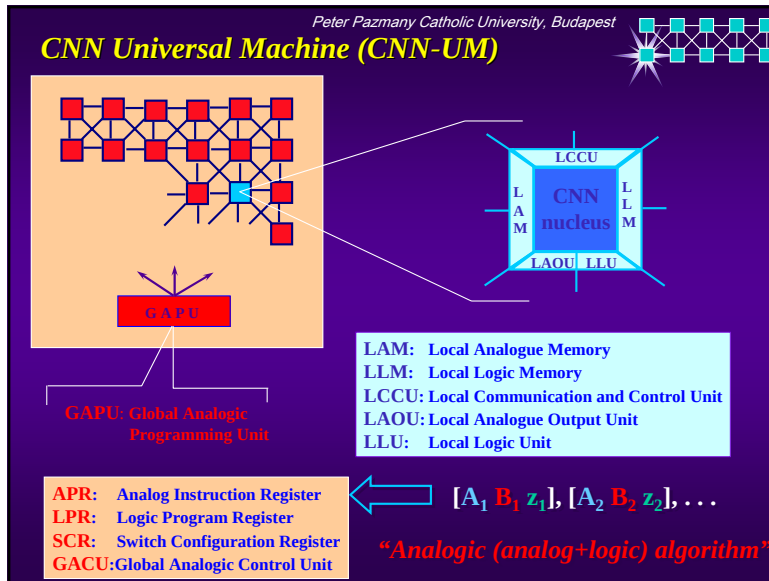
Global PDE (Sapiro et. al):

- the evolution of the system at some location depends also on global properties

$$\dot{\phi}_r(x, y, t) = \Gamma(\phi_r(x, y, t), A(x, y, t))$$

$$\{ \exists (x_0, y_0, t) \mid r \rightarrow 0 \Rightarrow \Gamma = \Gamma(x_0, y_0, t, A(.)) \wedge A(.) \neq 0 \}$$





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PDE formulation of reaction-diffusion processes

Reaction-diffusion type nonlinear PDE:

$$\frac{\partial \phi(x, y, t)}{\partial t} - \text{div}(c(\phi(x, y, t)) \text{grad}(\phi(x, y, t))) = \phi_0(x, y, t_0) + \mathfrak{I}(\phi(x, y, t))$$

Sub-classes ($c(\cdot) = c_0$):

I. $\phi_0(\cdot) = 0 \wedge \mathfrak{I}(\cdot) = 0$	$\Rightarrow$	linear diffusion equation
II. $\phi_0(\cdot) \neq 0 \wedge \mathfrak{I}(\cdot) = 0$	$\Rightarrow$	constrained linear diffusion equation
III. $\phi_0(\cdot) = 0 \wedge \mathfrak{I}(\cdot) \neq 0$	$\Rightarrow$	nonlinear trigger-wave equation
IV. $\phi_0(\cdot) \neq 0 \wedge \mathfrak{I}(\cdot) \neq 0$	$\Rightarrow$	constrained nonlinear trigger-wave equation

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Deriving coupled ODEs from PDEs I.

Reaction-diffusion type nonlinear ODE:

$$\frac{d\phi_{ij}(t)}{dt} = g(\phi_{ij}(t)) - \phi_{ij}(t) + \frac{c_1}{4}(\phi_{i-1j}(t) + \phi_{i+1j}(t) + \phi_{ij-1}(t) + \phi_{ij+1}(t)) + z_{ij}$$

$$\phi_{ij}(t) = f(x_{ij}(t)) \wedge g(\cdot) = c_0 f(\cdot) \wedge z_{ij} = z_0 + \sum_{kl \in N_1} b_{kl} \phi_{kl}(t_0)$$

Sub-classes:

I. $z_{ij} = 0 \wedge f(\phi) = \phi$	$\Rightarrow$	linear diffusion equation
II. $z_{ij} \neq 0 \wedge f(\phi) = \phi$	$\Rightarrow$	constrained linear diffusion equation
III. $z_{ij} = 0 \wedge f(\phi) = \text{sigm}(\phi)$	$\Rightarrow$	nonlinear trigger-wave equation
IV. $z_{ij} \neq 0 \wedge f(\phi) = \text{sigm}(\phi)$	$\Rightarrow$	constrained nonlinear trigger-wave equation

All implementable on the ACE4K 64x64 CNN-UM chip !



Deriving coupled ODEs from PDEs II.

Reaction-diffusion type nonlinear ODE:

$$\frac{d\phi_{ij}(t)}{dt} = g(\phi_{ij}(t)) - \phi_{ij}(t) + \frac{c_1}{4}(\phi_{i-1,j}(t) + \phi_{i+1,j}(t) + \phi_{i,j-1}(t) + \phi_{i,j+1}(t)) + z_{ij}$$

$$\phi_{ij}(t) = f(x_{ij}(t)) \wedge g(\cdot) = c_0 f(\cdot) \wedge z_{ij} = z_0 + \sum_{kl \in N_1} b_{kl} \phi_{kl}(t_0)$$

Templates (symmetric-isotropic class):

$$A = \begin{bmatrix} 0 & c_1 & 0 \\ c_1 & c_0 & c_1 \\ 0 & c_1 & 0 \end{bmatrix}; \quad B = \begin{bmatrix} b_2 & b_1 & b_2 \\ b_1 & b_0 & b_1 \\ b_2 & b_1 & b_2 \end{bmatrix}; \quad z_0$$

$c_0 = 0 \wedge c_1 > 0 \rightarrow \text{diffusion};$

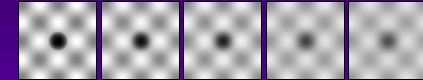
$c_0 > c_1 > 0 \rightarrow \text{trigger - waves}$



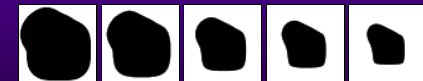
Computing with diffusion and waves - I. / derived from reaction-diffusion systems /

Examples:

Linear diffusion



Trigger-waves



Linear Diffusion Scale Space - I.

Diffusion (heat equation): $\frac{d}{dt} x_t(v_1, v_2) = \nabla^2 x_t(v_1, v_2)$

2D spatial Fourier-tr: $\frac{d}{dt} \tilde{X}_t(\Omega_1, \Omega_2) = -(\Omega_1^2 + \Omega_2^2) \tilde{X}_t(\Omega_1, \Omega_2)$

since: $\tilde{\nabla}^2(\Omega_1, \Omega_2) = -(\Omega_1^2 + \Omega_2^2)$

Solution in freq. domain: $\tilde{X}_t(\Omega_1, \Omega_2) = e^{-(\Omega_1^2 + \Omega_2^2)t} \tilde{X}_0(\Omega_1, \Omega_2)$

Solution in time domain: $x_t(v_1, v_2) = e^{-(v_1^2 + v_2^2)t/2} * x_0(v_1, v_2)$

The output at time t is the convolution
of the input by a Gaussian kernel function
(the width of G is parametrized by time)

$$\sigma = \sqrt{t}$$



Linear Diffusion Scale Space - II.

Autonomous CNN: $\frac{d}{dt} x_t(n_1, n_2) = \Lambda(n_1, n_2) * x_t(n_1, n_2)$

where:
$$\Lambda(n_1, n_2) = \begin{cases} A_{0,0} - 1 & n_1, n_2 \in (0,0) \\ A_{n_1, n_2} & n_1, n_2 \in S_r \\ 0 & \text{otherwise} \end{cases}$$

Discrete Space FT: $\frac{d}{dt} \tilde{X}_t(\omega_1, \omega_2) = \tilde{\Lambda}(\omega_1, \omega_2) \tilde{X}_t(\omega_1, \omega_2)$

Solution: $\tilde{X}_t(\omega_1, \omega_2) = e^{i\tilde{\Lambda}(\omega_1, \omega_2)t} \tilde{X}_0(\omega_1, \omega_2)$

$\tilde{\Lambda}(\omega_1, \omega_2)$ approximates the diffusion operator
(constraints: discrete space and limited size of the operator)

Example: $\tilde{\Lambda}(0,0) = 0$ $\Lambda = \begin{bmatrix} 0.5 & 1.0 & 0.5 \\ 1.0 & -6.0 & 1.0 \\ 0.5 & 1.0 & 0.5 \end{bmatrix} \Rightarrow \tilde{\Lambda} \approx -2(\omega_1^2 + \omega_2^2)$ **Laplace!**

Scale:
 $s \propto \sqrt{t}$



Multi-Scale Representations - I.

Gauss Decomposition

Base level (original image): $\tilde{G}^{(0)}(\omega_1, \omega_2) = \tilde{X}_0(\omega_1, \omega_2)$

p-th level (p=1,2,..P): $\tilde{G}^{(p)}(\omega_1, \omega_2) = \tilde{\Gamma}_{t_p}(\omega_1, \omega_2) \tilde{G}^{(0)}$

method:

$$\forall \sqrt{\omega_1^2 + \omega_2^2} \geq \pi : \tilde{\Gamma}_t(\omega_1, \omega_2) \leq K \quad \tilde{\Gamma}_t(\omega_1, \omega_2) = e^{i\tilde{\Lambda}(\omega_1, \omega_2)}$$

$$t_p = \frac{\ln K}{\tilde{\Lambda}(\pi/2^p, 0)} \quad \text{- to determine the stopping times for a given K and level p}$$



Multi-Scale Representations - II.

Laplace Decomposition

- DoG decomposition (by recursion from G decomposition)

$$p\text{-th level (p=1,2,..P): } L^{(p)} = \tilde{G}^{(p)} - \tilde{G}^{(p+1)}$$

- LoG decomposition (by applying the appr. Laplacian operator to each level of G decomposition)



Multi-Scale Representations - III.

Wavelet Representation

Wavelet transformation (1D): $\hat{f}(\xi, g) = |\xi|^{-1} \int f(v) h\left(\frac{v-g}{\xi}\right) dv$

Wavelet basis: $h_{\xi, g}(v) = |\xi|^{-1} h\left(\frac{v-g}{\xi}\right)$

- $h()$ satisfies an admissible and regularity condition

CNN wavelets derived from a low-pass - high-pass approach:

$$h_t(\omega_1, \omega_2) = \tilde{\Gamma}_t(\omega_1, \omega_2)(1 - \tilde{\Gamma}_t(\omega_1, \omega_2)) \quad \text{- band-pass!}$$

For a desired center frequency: $t = \frac{\ln(1/2)}{\tilde{\Lambda}(\omega_1^c, \omega_2^c)} \quad \text{- transient length}$



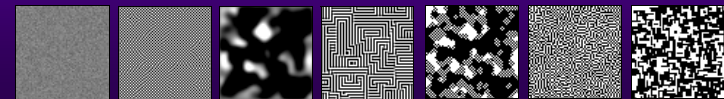
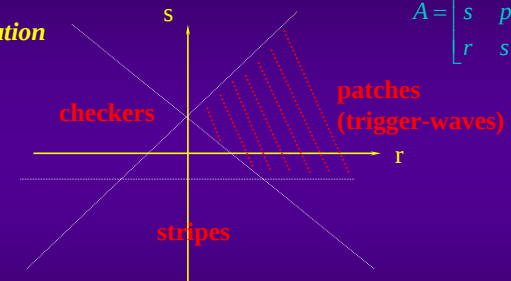
Computing with diffusion and waves - II.

/ derived from reaction-diffusion systems /

Examples:

Pattern formation

(p > 1)



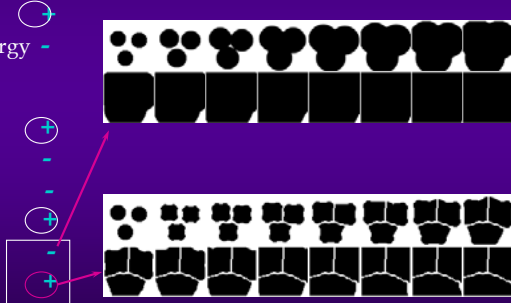


Trigger-waves as computing tools

Basic wave properties:

- reversibility
- conservation of energy
- conservation of amplitude and wave-front
- reflection
- interference
- diffraction
- annihilation

Controlling the annihilation property



Slice analysis based on active contour tracking

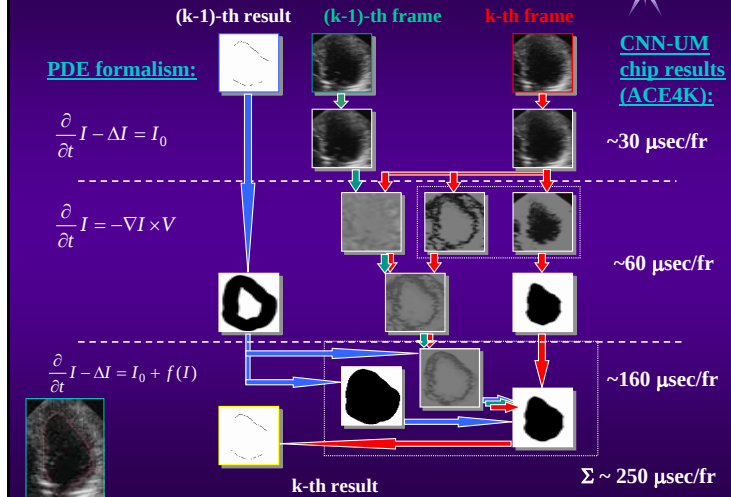


PDE formalism:

$$\frac{\partial}{\partial t} I - \Delta I = I_0$$

$$\frac{\partial}{\partial t} I = -\nabla I \times V$$

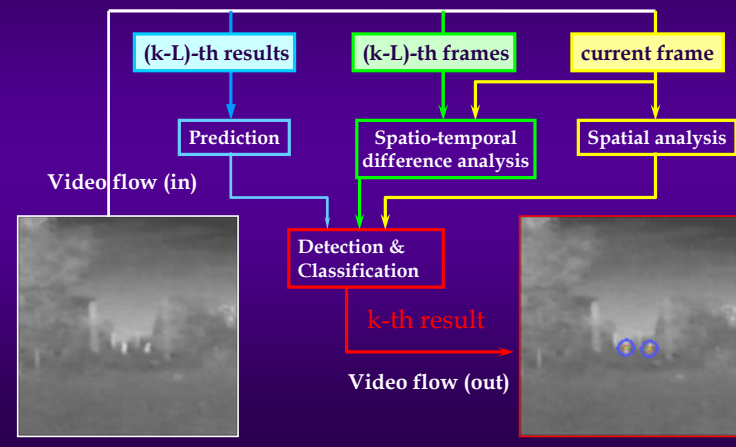
$$\frac{\partial}{\partial t} I - \Delta I = I_0 + f(I)$$



Target tracking experiments in a real scene (simulation)



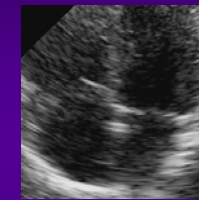
Task: Track "small" moving objects having "high" contrast



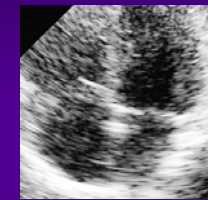
Histogram Modification with Embedded Morphological Processing: Motivations



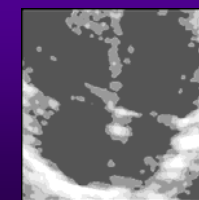
Original image:



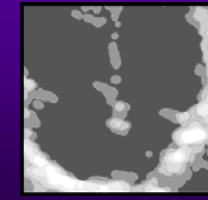
Normalized image:



Scales (3t),
8 gray-scale
levels:



Scales (5t),
8 gray-scale
levels:



PDE Formulation of Histogram Modification (Contrast Enhancement) with Denoising - I.

Sapiro & Caselles:

$$\frac{\partial \phi(x, y, t)}{\partial t} = \alpha \kappa + (N^2 - H(\phi(x, y, t))) - A[(v, w) : \phi(v, w, t) \geq \phi(x, y, t)]$$

where:

Φ - image intensity

$\kappa(\cdot)$ - diffusion term

$H(\cdot)$ - monotonic control function of histogram modification

$A(\cdot)$ - area (integral)

α, N - constants

$$\kappa = \text{div}(\text{grad}(\|\phi\|))$$

$$A = \iint_{\Omega} (\cdot) dx dy$$

PDE Formulation of Histogram Modification (Contrast Enhancement) with Denoising - II.

Steady-state solution (with $\alpha=0$):

$$A[(v, w) : \phi(v, w) \geq \phi(x, y)] = N^2 - H(\phi(x, y))$$

If $H = H_0 \phi = (N^2/M)\phi$ then the result is the histogram equalized image!

Global asymptotic stability:

$$U(\Phi) = \frac{1}{2} \int (\Phi(X) - \frac{1}{2}) dX - \frac{1}{4} \iint |\Phi(X) - \Phi(Z)| dX dZ$$

$U(\Phi)$ is a Lyapunov function!

PDE Formulation of Histogram Modification (Contrast Enhancement) with Denoising - III.

Derivation of nonlinear ODEs:

Case1 (global histogram equalization):

$$\text{Let: } \alpha = 0; H_0 = N^2 / M; N^2 = 1; M = 1;$$

$$\Rightarrow \frac{d\phi_{ij}(t)}{dt} = -\phi_{ij}(t) + (1 - A_{ij})$$

Case2 (global histogram equalization with denoising):

$$\text{Let: } \alpha = 1; \kappa = \text{div}(\text{grad}(\|\phi\|)); H_0 = N^2 / M; N^2 = 1; M = 1;$$

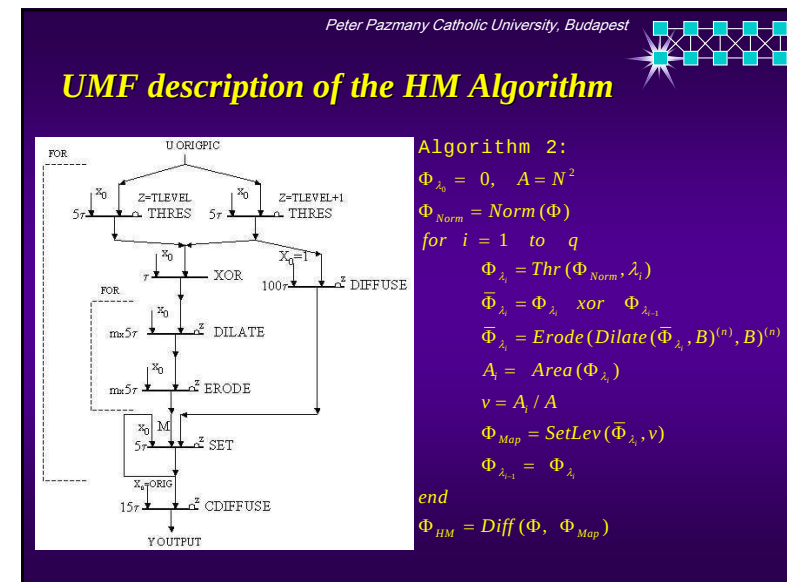
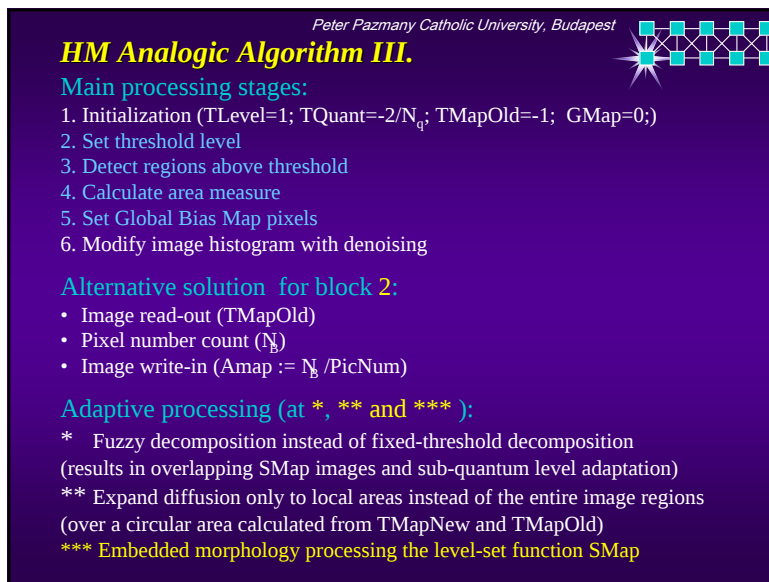
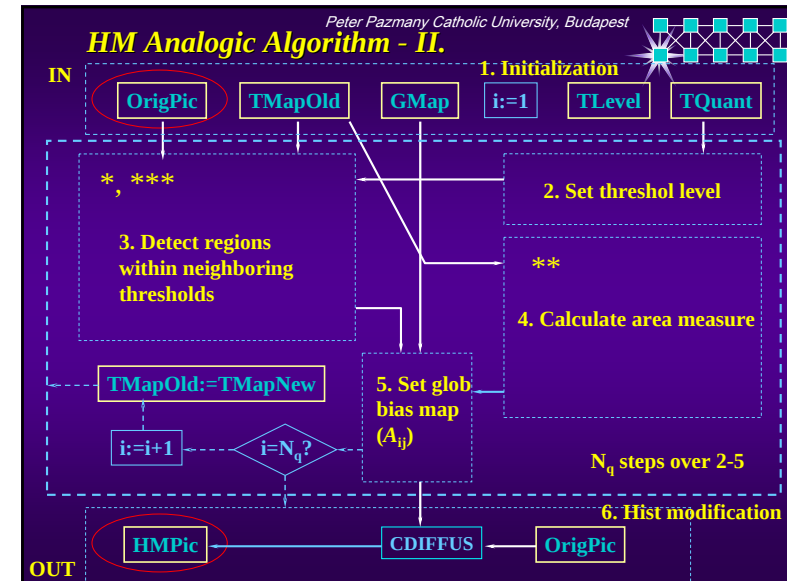
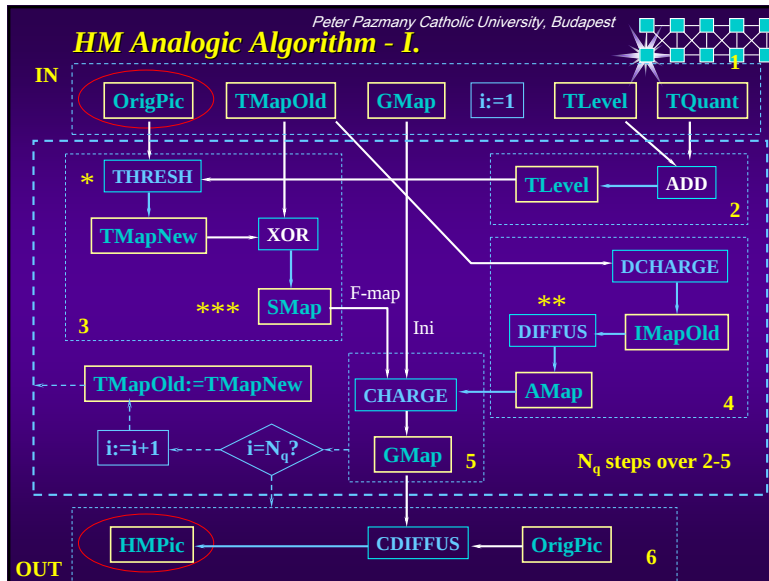
$$\Rightarrow \frac{d\phi_{ij}(t)}{dt} = -\phi_{ij}(t) + \frac{1}{4}(\phi_{i-1,j}(t) + \phi_{i+1,j}(t) + \phi_{i,j-1}(t) + \phi_{i,j+1}(t)) + (1 - A_{ij})$$

PDE Formulation of Histogram Modification (Contrast Enhancement) with Denoising - IV.

Computational aspects:

- The denoising term is a (nonlinear) diffusion equation formulation
- In both cases A_{ij} = **const during the evolution**, therefore should be calculated only once!
- Though A_{ij} is the output of a global transformation it is possible to give an approximation based on purely local (analog & logic) operations. Exploiting the global dynamics of the local analog operations results in further desirable properties!







Implementation of the HM Algorithm I.

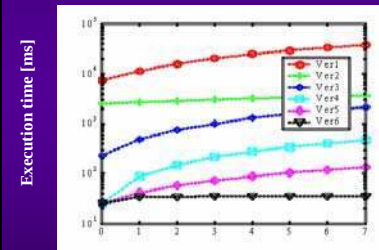
Different hardware-software configurations implemented:

- Version 1: MATCNN **MATLAB** Toolbox simulating all analog CNN dynamics μP : Pentium 1GHz
- Version 2: Version 1 except for simulating through the CNN fixed-points with an optimized **C-code**
- Version 3: Version 2 except for the **C-code** contains the entire algorithm.
- Version 4: Aladdin Professional with an optimized **C-code** that contains the entire algorithm running on a **DSP**
- Version 5: Version 4 except for the morphology operation is optimized at the **assembly** level
- Version 6: Version 4 except for the morphology operation is optimized for the **CNN-UM** chip
- Version 7: in Aladdin Professional running the entire algorithm on a **CNN-UM** chip (ongoing). μP : Alcatel ACE4k



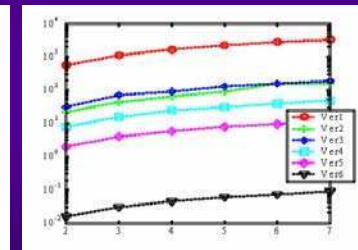
Implementation of the HM Algorithm II.

Execution time of Hmod algorithms ($q=8$)



Morphological steps (num)

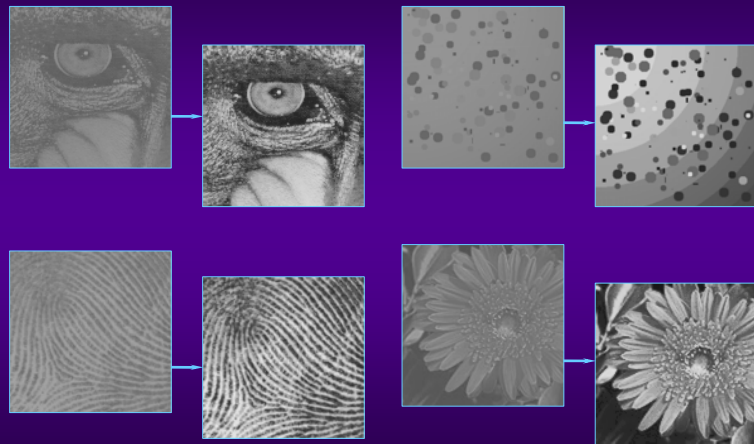
Execution time of binary morphology



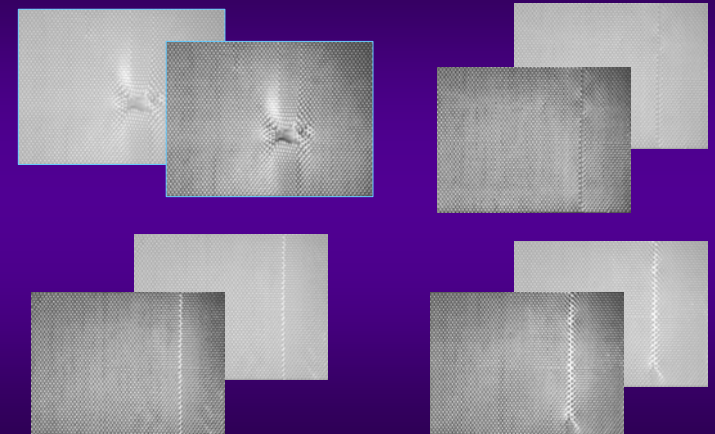
Morphological steps (num)



HM – examples I.



HM - examples II.





HM with Embedded Morphological Processing

Low contrast and noisy image (input):



Original image:



The number of morphological operation performed (0-4)

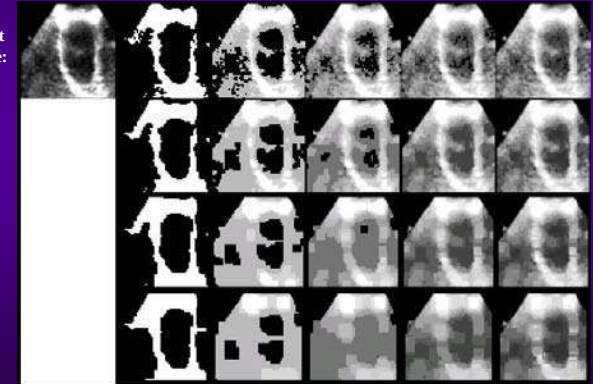
The number of equalization levels (32,16,8,4,2)



ACE4k chip experiments

The number of equalization levels (2,4,8,16,32)

Noisy input
echo image:



The number of morphological
operation performed (0-3)



Summary:

- Important classes of **local and global PDEs** describing calculations via image flows can be well approximated by local processing (with global dynamics) on a locally connected nonlinear net described by nonlinear ODEs
- **Diffusion and waves**, generated and controlled on silicon, can be viewed as flexible computing tools in solving various image processing problems
- Analogic CNN algorithms - **building on PDE formulation** - have been designed for contour detection, tracking, object classification and global histogram equalization with simultaneous denoising not exceeding the complexity of the ACE4K CNN-UM chip



This is not the end of the story!

Is the wave-equation realizable on silicon?

$$\frac{\partial^2 \phi_r}{\partial t^2}(x, y, t) = \Gamma(\phi_r(x, y, t))$$

$$\{ \forall (x_0, y_0, t) \mid r \rightarrow 0 \Rightarrow \Gamma = \Gamma(x_0, y_0, t) \}$$

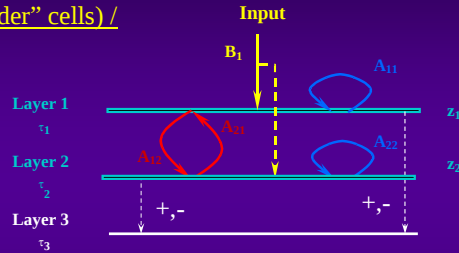
Things to come:

- A **2nd order/two layer CNN** described by nonlinear ODEs
- “**Complex cell**” CNN-UM chip (CICA1k - 2001)



The architecture I.

Two-layer (or “2nd order” cells) / 3-layer model



Main requirements:

- core: two mutually coupled 1st order RC cells
- 21 linear synapses on 8-connected square-grid
- nearest neighbor interaction
- double time-scale property
- constant and zero flux boundary condition
- single input (1st L or 2nd L), separate initial states



The architecture II.

System equations

$$C_1 \dot{x}_{1,ij} = -x_{1,ij} / R_1 + \sum_{kl \in N_1} A_{11,kl} y_{1,kl} + a_{21} y_{2,ij} + b_0 u_{ij} + z_1, \quad y_{1,ij} = f(x_{1,ij})$$

$$C_2 \dot{x}_{2,ij} = -x_{2,ij} / R_2 + \sum_{kl \in N_1} A_{22,kl} y_{2,kl} + a_{12} y_{1,ij} + z_2, \quad y_{2,ij} = f(x_{2,ij})$$

$$x_{3,ij} = f_a(x_{1,ij}, x_{2,ij})$$

$$\tau_1 = R_1 C_1, \quad \tau_2 = R_2 C_2, 1 \leq i \leq M, \quad 1 \leq j \leq M, 0 \leq |u_{ij}| \leq 1$$

$$\text{Chua - Yang: } 0 \leq |x_{ij}(0)| \leq 1, \quad \text{Full - range: } 0 \leq |x_{ij}(t \geq 0)| \leq 1,$$

Template format

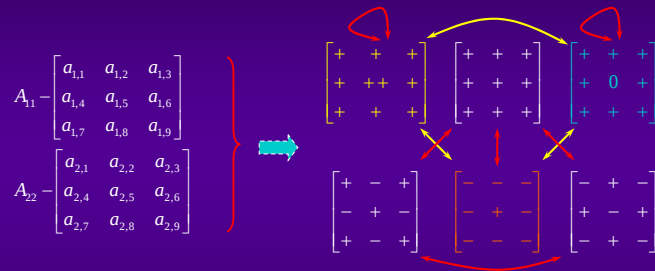
$$A_{11} = \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{1,4} & a_{1,5} & a_{1,6} \\ a_{1,7} & a_{1,8} & a_{1,9} \end{bmatrix}; \quad A_{22} = \begin{bmatrix} a_{2,1} & a_{2,2} & a_{2,3} \\ a_{2,4} & a_{2,5} & a_{2,6} \\ a_{2,7} & a_{2,8} & a_{2,9} \end{bmatrix}; \quad A_{12} = a_{12}; \quad A_{21} = a_{21};$$

$$B_1 = b_0; \quad z_1; \quad z_2; \quad \tau_1; \quad \tau_2$$



Multi-layer templates

Configurations (determined by fixed A templates)

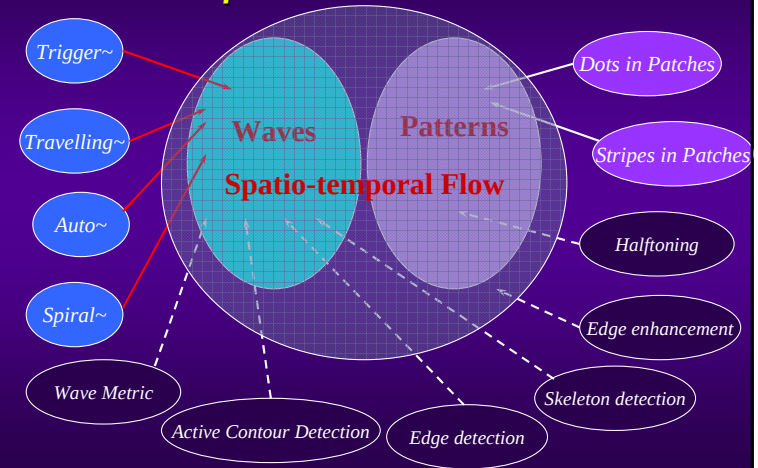


Tuned parameters

$$A_{12} = a_{12}; \quad A_{21} = a_{21}; \quad B_1 = b_0; \quad z_1; \quad z_2; \quad \tau_1; \quad \tau_2$$

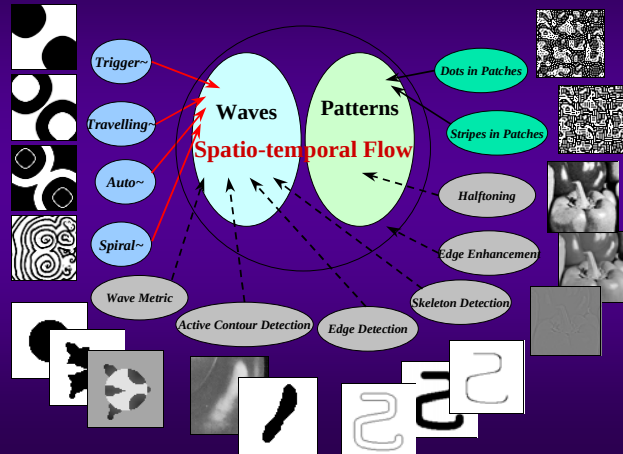


The Universe of Phenomena in a 2nd Order CNN





The Universe of Phenomena in a 2nd Order CNN



Wave Phenomena

/ combining trigger-waves travelling at different speed /

Examples:

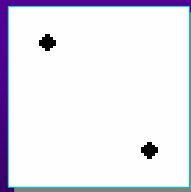
- trigger-waves
- travelling-waves
- spiral-waves
- auto-waves



Trigger-waves

$$A_{11} = A_{22} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{12} = 1.0; \quad A_{21} = 0;$$

$$B_1 = 0; \quad z_1 = 3.75; \quad z_2 = 3.75; \quad \tau_1 / \tau_2 = 5$$



Layer 1



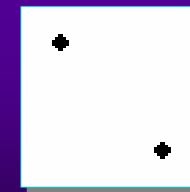
Layer 2



Travelling-waves

$$A_{11} = A_{22} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{12} = 3.0; \quad A_{21} = -5;$$

$$B_1 = 0; \quad z_1 = -1.25; \quad z_2 = 2.25; \quad \tau_1 / \tau_2 = 5$$



Layer 1



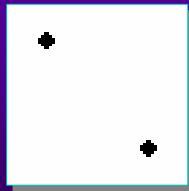
Layer 2



Spiral-waves

$$A_{11} = A_{22} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{12} = 5.5; \quad A_{21} = -17.5;$$

$$B_1 = 0; \quad z_1 = -1.25; \quad z_2 = -1.25; \quad \tau_1 / \tau_2 = 5$$



Layer 1



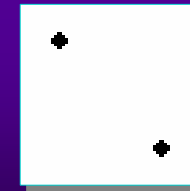
Layer 2



Auto-waves (ChY-model)

$$A_{11} = A_{22} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{12} = 5.5; \quad A_{21} = -5;$$

$$B_1 = 0; \quad z_1 = -1.25; \quad z_2 = -1.25; \quad \tau_1 / \tau_2 = 5$$



Layer 1



Layer 2



Pattern Formation

/ combining low-pass, high-pass and band-pass type filters /

Examples:

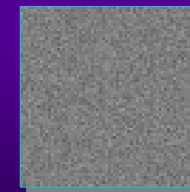
- patches and dots in patches
- patches and stripes in patches



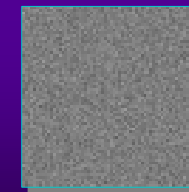
Patches and dots in patches

$$A_{11} = \begin{bmatrix} 0.5 & 1 & 0.5 \\ 1 & 2 & 1 \\ 0.5 & 1 & 0.5 \end{bmatrix}; \quad A_{22} = \begin{bmatrix} -0.5 & -1 & -0.5 \\ -1 & 2 & -1 \\ -0.5 & -1 & -0.5 \end{bmatrix}; \quad A_{12} = 4; \quad A_{21} = 0;$$

$$B_1 = 0; \quad z_1 = 0; \quad z_2 = 0; \quad \tau_1 / \tau_2 = 0.1$$



Layer 1



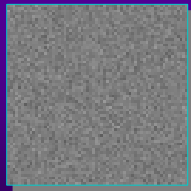
Layer 2



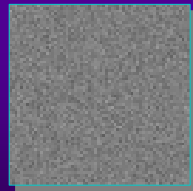
Patches and stripes in patches

$$A_{11} = \begin{bmatrix} 0.5 & 1 & 0.5 \\ 1 & 2 & 1 \\ 0.5 & 1 & 0.5 \end{bmatrix}; \quad A_{22} = \begin{bmatrix} -0.5 & 0 & -0.5 \\ 0 & 2 & 0 \\ -0.5 & 0 & -0.5 \end{bmatrix}; \quad A_{12} = 1; \quad A_{21} = 0;$$

$$B_1 = 0; \quad z_1 = 0; \quad z_2 = 0; \quad \tau_1 / \tau_2 = 0.1$$



Layer 1



Layer 2



Image Processing

/ combining diffusion, trigger-waves and various filtering effects /

Examples:

- edge enhancement
- halftoning
- active contour detection
- wave-metric
- edge detection
- skeletonization



Edge enhancement (outer retina model)

$$A_{11} = A_{22} = \begin{bmatrix} 0.05 & 0.20 & 0.05 \\ 0.20 & 0.00 & 0.20 \\ 0.05 & 0.20 & 0.05 \end{bmatrix}; \quad A_{12} = 0.1; \quad A_{21} = -5.0;$$

$$B_1 = 1.0; \quad z_1 = 0; \quad z_2 = 0; \quad \tau_1 / \tau_2 = 10;$$



Input



Layer 1



Layer 2



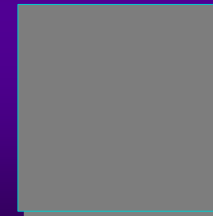
Halftoning

$$A_{11} = \begin{bmatrix} -0.36 & -0.60 & -0.36 \\ -0.60 & 1.05 & -0.60 \\ -0.36 & -0.60 & -0.36 \end{bmatrix}; \quad A_{22} = \begin{bmatrix} 0.05 & 0.20 & 0.05 \\ 0.20 & 0.00 & 0.20 \\ 0.05 & 0.20 & 0.05 \end{bmatrix}; \quad \tau_1 / \tau_2 = 10;$$

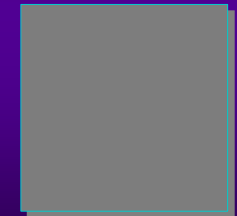
$$A_{12} = 1.0; \quad A_{21} = -1.0; \quad B_1 = 7.0; \quad z_1 = 0; \quad z_2 = 0;$$



Input



Layer 1



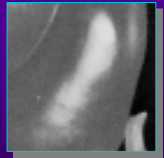
Layer 2



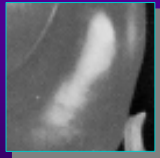
Active Contour Detection

$$A_{11} = 0.5 \begin{bmatrix} 0.05 & 0.20 & 0.05 \\ 0.20 & 0.00 & 0.20 \\ 0.05 & 0.20 & 0.05 \end{bmatrix}; \quad A_{22} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad \tau_1 / \tau_2 = 1.0;$$

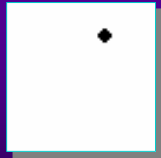
$$A_{12} = -2.5; \quad A_{21} = -0.1; \quad B_1 = 1.0; \quad z_1 = 0; \quad z_2 = 1.25$$



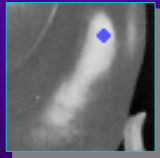
Input



Layer 1



Layer 2



Result & Inp



Wave-metric

$$A_{11} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{22} = 0.0; \quad \tau_1 / \tau_2 = 0.1;$$

$$A_{12} = -0.5; \quad A_{21} = 0.0; \quad B_1 = 2.0; \quad z_1 = 1.75; \quad z_2 = -1.0;$$



Obj1



Obj2



Input



Layer 1



Layer 2



Edge detection

$$A_{11} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{22} = \begin{bmatrix} -0.1 & -0.1 & -0.1 \\ -0.1 & 2.3 & -0.1 \\ -0.1 & -0.1 & -0.1 \end{bmatrix}; \quad \tau_1 / \tau_2 = 1.0;$$

$$A_{12} = -1.0; \quad A_{21} = 0.0; \quad B_1 = 0.0; \quad z_1 = 3.75; \quad z_2 = 0.0;$$



Input



Layer 1



Layer 2



Skeletonization

$$A_{11} = \begin{bmatrix} 0.25 & 0.25 & 0.25 \\ 0.25 & 3.00 & 0.25 \\ 0.25 & 0.25 & 0.25 \end{bmatrix}; \quad A_{22} = \begin{bmatrix} -0.25 & -0.25 & -0.25 \\ -0.25 & 5.4 & -0.25 \\ -0.25 & -0.25 & -0.25 \end{bmatrix}; \quad \tau_1 / \tau_2 = 0.5;$$

$$A_{12} = -2.5; \quad A_{21} = 0.0; \quad B_1 = 0.0; \quad z_1 = 3.75; \quad z_2 = 0.0;$$



Input



Layer 1



Layer 2



Summary

A *double time-scale, single-input 2nd order/3-layer CNN model (with two mutually coupled 1st order RC cells and max. 21 synapses)* is capable to reproduce a number of complex wave and pattern formation phenomena, and can be used as the core architecture in various meaningful image processing operations.



Higher complexity cellular chips could also be built and used in PDE approximation, modeling and engineering applications.