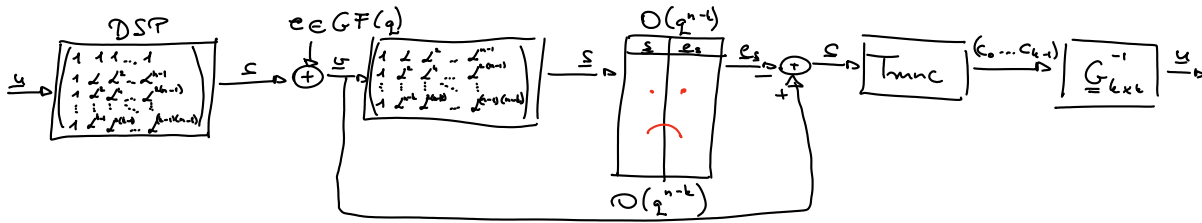


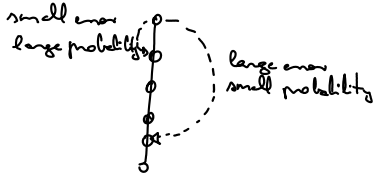
# RS code

2016. október 12., szerda 16:22



$$\mathbb{E}_s = \{e : H e^T = s^T\}; e_s : \max_{e \in \mathbb{E}_s} p(e)$$

that's the part we don't like



$$e = (0, 0, 1, 0, 1, 0)$$

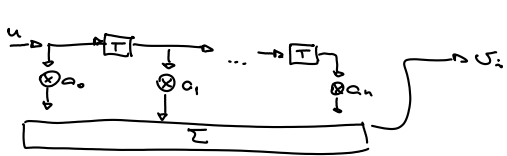
$$e^T = (0, 1, 1, 1, 0, 0)$$

Design: given 't' errors

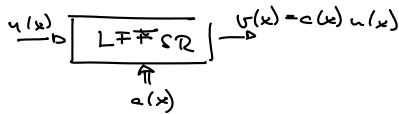
$$n = q-1; n-k = 2t; q \text{ prime}$$

$$\Rightarrow L \in GF(q)$$

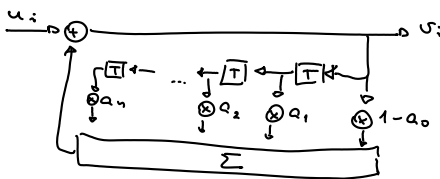
## Linear FeedForward Shift Register



$$\begin{aligned} i=0 & v_0 = a_0 u_0 \\ i=1 & v_1 = a_0 u_0 + a_1 u_1 \\ i=2 & v_2 = \\ & \vdots \\ i & v_i = \sum_{j=0}^i a_j u_{i-j} \end{aligned} \Rightarrow v(x) = a(x) u(x)$$



## Linear FeedBack Shift Register (LFB SR)



$$v_i = (1-a_0)v_i - a_1 v_{i-1} - a_2 v_{i-2} - \dots - a_n v_{i-n} + u_i$$

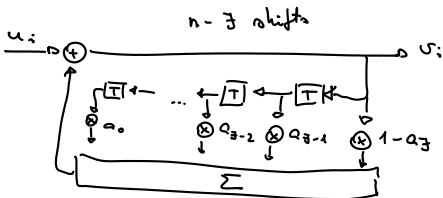
$$v_i - (1-a_0)v_i + a_1 v_{i-1} + a_2 v_{i-2} + \dots + a_n v_{i-n} = u_i$$

$$\sum_{j=0}^n a_j v_{i-j} = u_i$$

$$a(x) v(x) = u(x) \Rightarrow v(x) = \frac{u(x)}{a(x)}$$



## Linear FeedBack Shift Register with remainder (LFB SR w.r.)



$$u(x) = v(x)a(x) + r(x)$$

$$\deg u(x) = n >$$

Example: in  $GF(5)$

$$(x^3 + 4x + 4) : (x^2 + 2x + 3) = x + 3$$

$$a(x) \Rightarrow a_0 \Rightarrow 1 - a_0 = 1 - 3 = -2 = 3$$

$$i=0 \Rightarrow v_0 = 3v_0 + 4$$

$$\Rightarrow v_0 = 4$$

